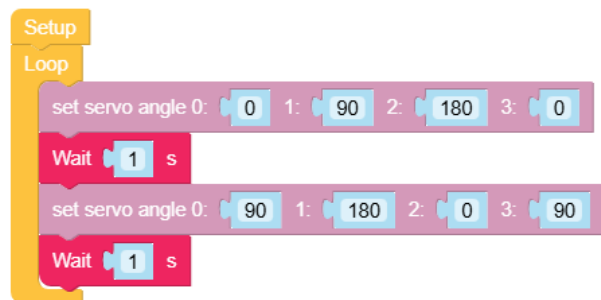


Hat Puppyc

Example

Changes the angle of all servos every second.



```
from m5stack import *
from m5ui import *
from uiflow import *
import time
import hat

setScreenColor(0x111111)

hat_puppyC_0 = hat.get(hat.PUPPY)

while True:
    hat_puppyC_0.SetAllAngle(0, 90, 180, 0)
    wait(1)
    hat_puppyC_0.SetAllAngle(90, 180, 0, 90)
    wait(1)
    wait_ms(2)
```

API

set servo angle 0: 0 1: 0 2: 0 3: 0

```
hat_puppyC_0.SetAllAngle(0, 0, 0, 0)
```

- Sets the angle of multiple servos simultaneously, from servo 0 to 3, where each value represents the rotation angle for each servo.

Set 0 servo rotate 0

```
hat_puppyC_0.SetAngle(0, 0)
```

- Sets the rotation angle of a specific servo. You can specify the servo number and set its rotation angle.